

为叙述方便，首先证明如下的

引理 1 设 $P_i(\cos 2\theta_i, \sin 2\theta_i)$, $\theta_i \in (0, \frac{\pi}{2})$ 且 θ_i 各不相同, $i=1, 2, 3, 4$. 直线 P_1P_2 与 P_3P_4 的交点为 $A(x_A, y_A)$, 则

$$\begin{cases} x_A = \frac{\sin(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2) \sin(\theta_3 + \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} \\ y_A = \frac{\cos(\theta_1 - \theta_2) \cos(\theta_3 + \theta_4) - \cos(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} \end{cases}.$$

证明 以下仅对直线 P_1P_2 与 P_3P_4 斜率存在的情形给出证明, 斜率不存在时, 容易验证结论成立.

P_1P_2 的斜率为: $\frac{\sin 2\theta_2 - \sin 2\theta_1}{\cos 2\theta_2 - \cos 2\theta_1} = -\frac{\cos(\theta_1 + \theta_2)}{\sin(\theta_1 + \theta_2)}$, 直线 P_1P_2 的方程为:

$$y - \sin 2\theta_1 = -\frac{\cos(\theta_1 + \theta_2)}{\sin(\theta_1 + \theta_2)}(x - \cos 2\theta_2), \quad \text{整} \quad \text{理} \quad \text{得}$$

$$y = -\frac{\cos(\theta_1 + \theta_2)}{\sin(\theta_1 + \theta_2)}x + \frac{\cos(\theta_1 - \theta_2)}{\sin(\theta_1 + \theta_2)} \quad \dots \dots \dots \textcircled{1}$$

同理, 直线 P_3P_4 的方程为

$$y = -\frac{c}{s} \frac{\theta_3 + i\theta}{\theta_3 + i\theta} x + \frac{s_4}{n_4} \frac{\theta + i\theta}{\theta + i\theta} \quad \dots \dots \dots \textcircled{2}$$

由①②消去 y 得, $x_A = \frac{\sin(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2) \sin(\theta_3 + \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)}$, 将 x_A 代入

①得

$$\begin{aligned} y &= -\frac{\cos(\theta_1 + \theta_2)}{\sin(\theta_1 + \theta_2)} \cdot \frac{\sin(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2) \sin(\theta_3 + \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} + \frac{\cos(\theta_1 - \theta_2)}{\sin(\theta_1 + \theta_2)} \\ &= \frac{1}{\sin(\theta_1 + \theta_2)} \cdot [\cos(\theta_1 - \theta_2) - \frac{\cos(\theta_1 + \theta_2)(\sin(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2) \sin(\theta_3 + \theta_4))}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)}] \quad \dots \dots \dots \textcircled{3} \end{aligned}$$

通分, 并注意到 $\cos(\theta_1 - \theta_2) \cdot \sin(\theta_1 + \theta_2 - \theta_3 - \theta_4) = \cos(\theta_1 - \theta_2) \sin((\theta_1 + \theta_2) - (\theta_3 + \theta_4))$

$= \cos(\theta_1 - \theta_2) \sin(\theta_1 + \theta_2) \cos(\theta_3 + \theta_4) - \cos(\theta_1 - \theta_2) \cos(\theta_1 + \theta_2) \sin(\theta_3 + \theta_4)$, 所以③可化

为 $y = \frac{\cos(\theta_1 - \theta_2)\cos(\theta_3 + \theta_4) - \cos(\theta_1 + \theta_2)\sin(\theta_3 - \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)}$, 此即 y_A , 引理 1 证毕.

引理 2 设平面直角坐标系中三点 $A(x_A, y_A), P(x_P, y_P), D(x_D, y_D)$ 的坐标为依次为

$$\begin{cases} x_A = \frac{\sin(\theta_1 + \theta_2)\cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2)\sin(\theta_3 + \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} \\ y_A = \frac{\cos(\theta_1 - \theta_2)\cos(\theta_3 + \theta_4) - \cos(\theta_1 + \theta_2)\cos(\theta_3 - \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} \end{cases}, \quad \begin{cases} x_P = \frac{\cos(\theta_1 + \theta_3)}{\cos(\theta_1 - \theta_3)}, \\ y_P = \frac{\sin(\theta_1 + \theta_3)}{\cos(\theta_1 - \theta_3)} \end{cases}$$

$$\begin{cases} x_D = \frac{\sin(\theta_2 + \theta_3)\cos(\theta_4 - \theta_1) - \cos(\theta_2 - \theta_3)\sin(\theta_4 + \theta_1)}{\sin(\theta_2 + \theta_3 - \theta_4 - \theta_1)} \\ y_D = \frac{\cos(\theta_2 - \theta_3)\cos(\theta_4 + \theta_1) - \cos(\theta_2 + \theta_3)\cos(\theta_4 - \theta_1)}{\sin(\theta_2 + \theta_3 - \theta_4 - \theta_1)} \end{cases}, \text{ 则 } A, P, D \text{ 三点共线.}$$

证明 记 $a = \sin(\theta_1 + \theta_2)\cos(\theta_3 - \theta_4) - \cos(\theta_1 - \theta_2)\sin(\theta_3 + \theta_4)$,

$$a' = \cos(\theta_1 - \theta_2)\cos(\theta_3 + \theta_4) - \cos(\theta_1 + \theta_2)\cos(\theta_3 - \theta_4),$$

$$d = \sin(\theta_2 + \theta_3)\cos(\theta_4 - \theta_1) - \cos(\theta_2 - \theta_3)\sin(\theta_4 + \theta_1),$$

$$d' = \cos(\theta_2 - \theta_3)\cos(\theta_4 + \theta_1) - \cos(\theta_2 + \theta_3)\cos(\theta_4 - \theta_1).$$

$$p = \cos(\theta_1 + \theta_3), \quad p' = \sin(\theta_1 + \theta_3), \quad s = \sin(\theta_1 + \theta_2 - \theta_3 - \theta_4), \quad s' = \sin(\theta_2 + \theta_3 - \theta_4 - \theta_1),$$

$$c = \cos(\theta_1 - \theta_3).$$

因为

$$a = \frac{1}{2}[\sin(\theta_1 + \theta_2 + \theta_3 - \theta_4) + \sin(\theta_1 + \theta_2 - \theta_3 + \theta_4)] - \frac{1}{2}[\sin(\theta_3 + \theta_4 + \theta_1 - \theta_2) + \sin(\theta_3 + \theta_4 - \theta_1 + \theta_2)]$$

$$d = \frac{1}{2}[\sin(\theta_2 + \theta_3 + \theta_4 - \theta_1) + \sin(\theta_2 + \theta_3 - \theta_4 + \theta_1)] - \frac{1}{2}[\sin(\theta_2 + \theta_4 + \theta_1 - \theta_3) + \sin(\theta_2 + \theta_4 - \theta_1 + \theta_3)]$$

$$, \text{ 所以 } a + d = \sin(\theta_1 + \theta_2 + \theta_3 - \theta_4) - \sin(\theta_3 + \theta_4 + \theta_1 - \theta_2) = 2\cos(\theta_1 + \theta_3)\sin(\theta_2 - \theta_4)$$

$$a + d + p = (2\sin(\theta_2 - \theta_4) + 1)\cos(\theta_1 + \theta_3) = (2\sin(\theta_2 - \theta_4) + 1)p,$$

$$\text{同理 } a' + d' + p' = (2\cos(\theta_2 - \theta_4) + 1)\sin(\theta_1 + \theta_3) = (2\sin(\theta_2 - \theta_4) + 1)p',$$

$$s + s' + c = 2\sin(\theta_2 - \theta_4)\cos(\theta_1 - \theta_3) + \cos(\theta_1 - \theta_3) = (2\sin(\theta_2 - \theta_4) + 1)\cos(\theta_1 - \theta_3)$$

$$= (2\sin(\theta_2 - \theta_4) + 1)c.$$

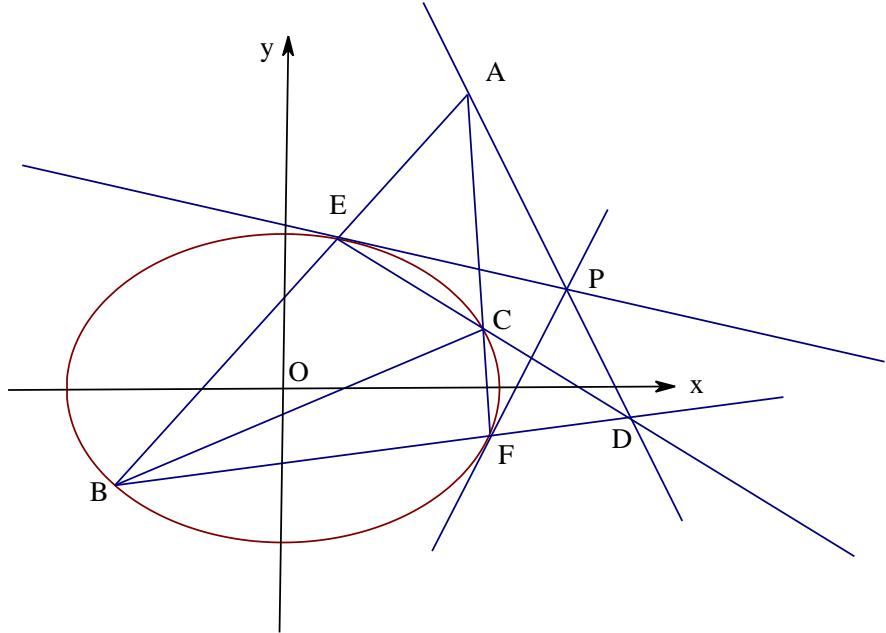
因为

$$\begin{aligned}
\Delta(A, D, P) &= \begin{vmatrix} x_A & y_A & 1 \\ x_D & y_D & 1 \\ x_P & y_P & 1 \end{vmatrix} = \begin{vmatrix} \frac{a}{s} & \frac{a'}{s} & 1 \\ \frac{d}{s'} & \frac{d'}{s'} & 1 \\ \frac{p}{c} & \frac{p'}{c} & 1 \end{vmatrix} = \\
&= \frac{1}{ss'c} \begin{vmatrix} a & a' & s \\ d & d' & s' \\ p & p' & c \end{vmatrix} = \frac{1}{ss'c} \begin{vmatrix} a+d+p & a'+d'+p' & s+s'+c \\ d & d' & s' \\ p & p' & c \end{vmatrix} \\
&= \frac{2\sin(\theta_2 - \theta_1) + 1}{ss'c} \begin{vmatrix} p & p' & c \\ d & d' & s' \\ p & p' & c \end{vmatrix} = 0, \text{ 所以 } A(x_A, y_A), P(x_P, y_P), D(x_D, y_D) \text{ 三点共线, 引理}
\end{aligned}$$

2 证毕.

以下利用引理 1 及引理 2 给原题的证明.

问题: 如图, BC 是椭圆的弦, AB, AC 所在的直线与椭圆交于 E, F , 过点 E, F 分别作椭圆的切线交于一点 P . 直线 AP 与 BF 交于一点 D , 则 D, C, E 三点共线.



证明 只要证明 A, P, D 三点共线.

设 椭 圆 的 方 程 为 $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ ($a > b > 0$). 取

$E(a \cos 2\theta_1, b \sin 2\theta_1)$, $B(a \cos 2\theta_2, b \sin 2\theta_2)$,

$F(a \cos 2\theta_3, b \sin 2\theta_3), C(a \cos 2\theta_4, b \sin 2\theta_4)$, 则直线 EB 的斜率为

$$\frac{b \sin 2\theta_2 - b \sin 2\theta_1}{a \cos 2\theta_2 - a \cos 2\theta_1} = \frac{b}{a} \cdot \frac{2 \cos(\theta_2 + \theta_1) \sin(\theta_2 - \theta_1)}{-2 \sin(\theta_2 + \theta_1) \sin(\theta_2 - \theta_1)} = -\frac{b}{a} \cdot \frac{\cos(\theta_1 + \theta_2)}{\sin(\theta_1 + \theta_2)}, \text{ 直线 } EB \text{ 的方程}$$

$$y - b \sin 2\theta_1 = -\frac{b}{a} \cdot \frac{\cos(\theta_2 + \theta_1)}{\sin(\theta_2 + \theta_1)} (x - a \cos 2\theta_1) \quad , \quad \text{即}$$

同 理 , 直 线 FC 的 方 程 为

$$y = -\frac{b}{a} \cdot \frac{\cos(\theta_3 + \theta_4)}{\sin(\theta_3 + \theta_4)} x + b \cdot \frac{\cos(\theta_3 - \theta_4)}{\sin(\theta_3 + \theta_4)} \quad \dots \dots \dots \quad (5)$$

由④⑤得 BE, FC 的交点 $A(x_A', y_B')$ 的坐标可以用引理 2 中的 x_A, y_A 表示为

$$\begin{cases} x_A' = a \cdot \frac{[\sin(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4) - \cos(\theta_1 + \theta_2) \sin(\theta_3 + \theta_4)]}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} = ax_A \\ y_A' = b \cdot \frac{\cos(\theta_1 - \theta_2) \cos(\theta_3 + \theta_4) - \cos(\theta_1 + \theta_2) \cos(\theta_3 - \theta_4)}{\sin(\theta_1 + \theta_2 - \theta_3 - \theta_4)} = by_A \end{cases}$$

同理，直线 BF, EC 的交点 $D(x_D, y_D)$ 的坐标为

$$\begin{cases} x_D' = a \cdot \frac{\sin(\theta_2 + \theta_3) \cos(\theta_4 - \theta_1) - \cos(\theta_2 - \theta_3) \sin(\theta_4 + \theta_1)}{\sin(\theta_2 + \theta_3 - \theta_4 - \theta_1)} = ax_D \\ y_D' = b \cdot \frac{\cos(\theta_2 - \theta_3) \cos(\theta_4 + \theta_1) - \cos(\theta_2 + \theta_3) \cos(\theta_4 - \theta_1)}{\sin(\theta_2 + \theta_3 - \theta_4 - \theta_1)} = by_D \end{cases}$$

过 E, F 的两切线的交点为 $\begin{cases} y_P = b \cdot \frac{\cos(\theta_1 - \theta_3)}{\sin(\theta_1 + \theta_3)} = b y_P \\ y_P = b \cdot \frac{\cos(\theta_1 - \theta_3)}{\cos(\theta_1 - \theta_3)} = 1 \end{cases}$, 由引理 2 的知, $\begin{vmatrix} x_D & y_D & 1 \\ x_P & y_P & 1 \end{vmatrix} = 0$,

$$\text{所以, } \Delta(A, D, P) = \begin{vmatrix} x_A & y_A & 1 \\ x_D & y_D & 1 \\ x_P & y_P & 1 \end{vmatrix} = \begin{vmatrix} ax_A & by_A & 1 \\ ax_D & by_D & 1 \\ ax_P & by_P & 1 \end{vmatrix} = ab \begin{vmatrix} x_A & y_A & 1 \\ x_D & y_D & 1 \\ x_P & y_P & 1 \end{vmatrix} = 0, \text{ 即 } A, P, D \text{ 共线.}$$